

Dependability Modelling and Assessment of Avionics Systems with Altarica.

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General Problem

- Avionics are complex systems
 - A380 (safety critical avionics):
 - +100 computers connected to the main Aircraft network,
 - ~10 000 data flows transmitted over the network
- Structured Design
 - Modular design
 - Systems : Flight Control, Flight Management, Flight parameters, ...
 - Layered design
 - functional architecture/allocation/ hardware architecture
- Complex Design Process
 - Several actors:
 - System designers -> functional architecture
 - Platform designers -> hardware architecture
 - Integrator -> allocation

General Goal

- Support the safety assessment of avionics systems
 - using Altarica models
 - and taking into account the current design process

- Apply the approach on case-studies
 - Dassault Mirage Terrain Following/Terrain Avoidance
 - Airbus systems (ADIRS, Fuel On Board,...)
 - Astrium ATV (Automatic Transfer Vehicle)

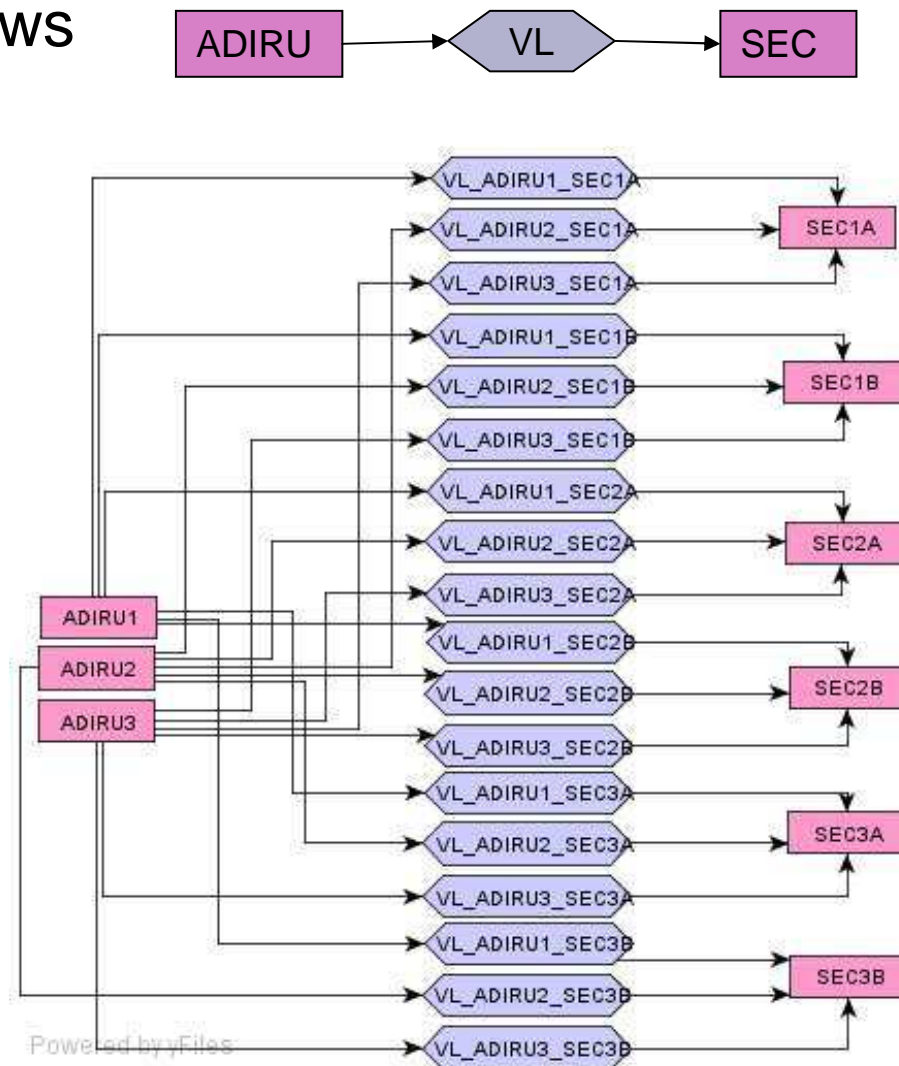
Overview

- Avionics Platform Design
 - Functional and hardware description
 - Allocation
- Safe Resource Allocation Process
 - Failure Propagation Modelling
 - Safety Requirements Validation
 - Independence requirement derivation
- Advanced Topics
 - Allocation Generation by Constraint Solving
 - Installation related risks
 - Automatical production of Altarica models
 - Middleware Modelling

Functional Architecture

- Function and Data flows

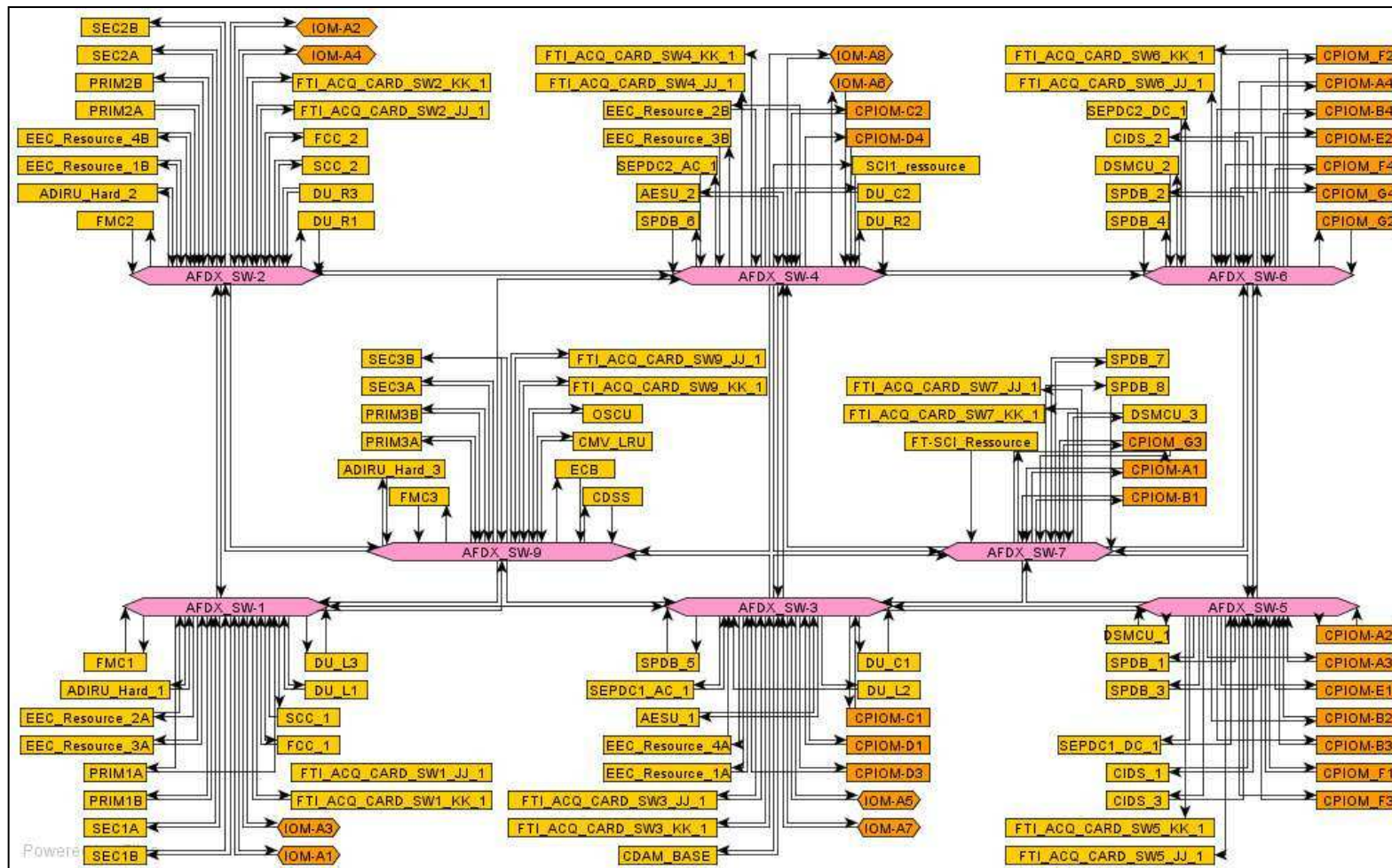
- ADIRU: x3
- SEC: x6
- VL : x18



Hardware Architecture

Interconnected resources

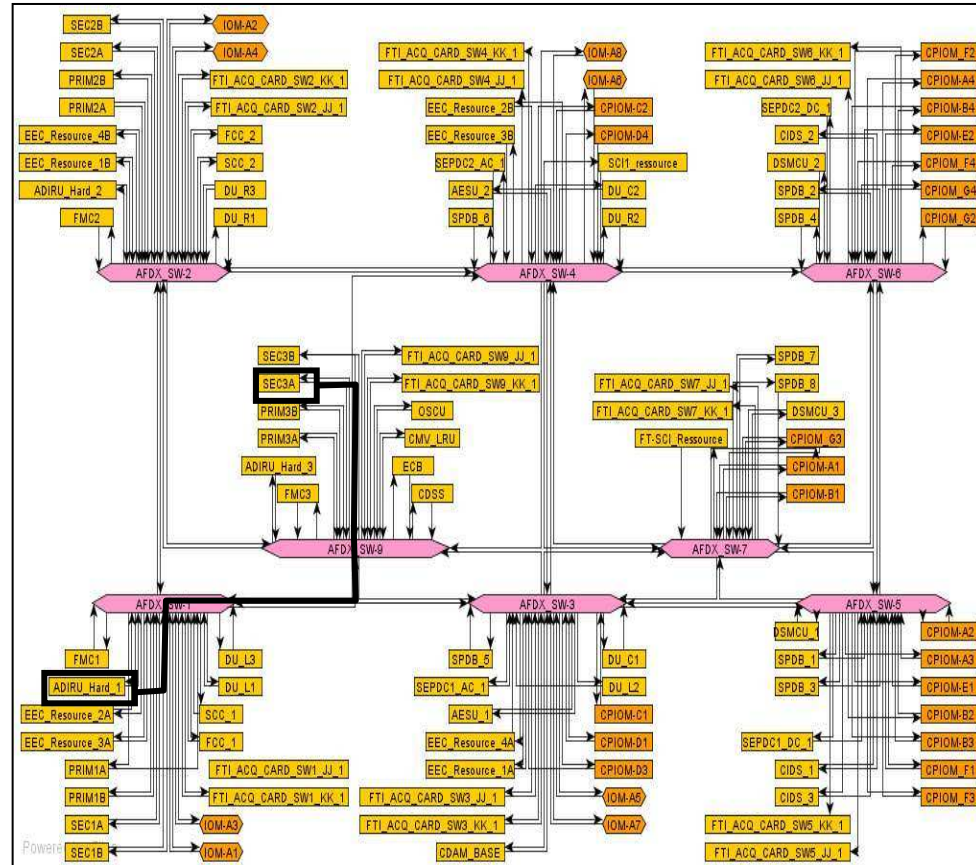
- Bus, Switch, CPU, ...



Allocation

- Described as tables
 - well formalized at detailed design stages
 - but often missing at earlier design stages

VL_ADIRU1_SEC3A :
 ADIRU_Hard_1, AFDX_SW-1, AFDX_SW-9, SEC3A

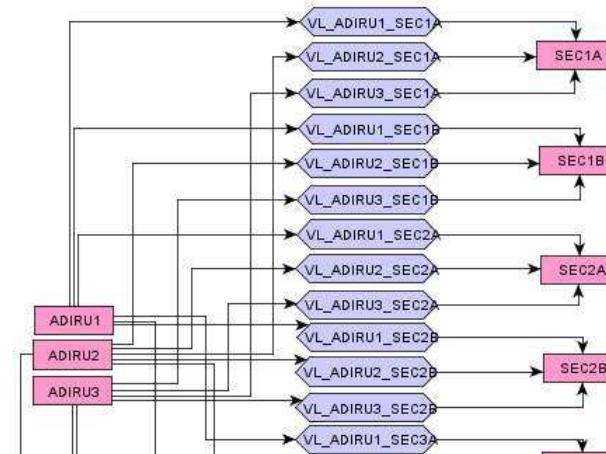


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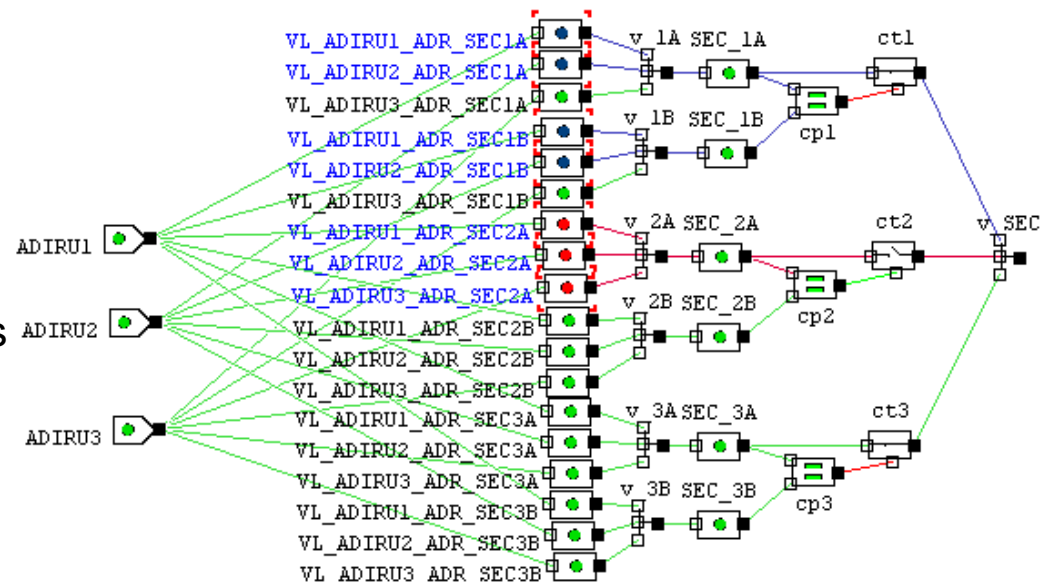
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Functional Architecture Safety Model

- Failure Propagation Model built using predefined nodes in an Altarica Library



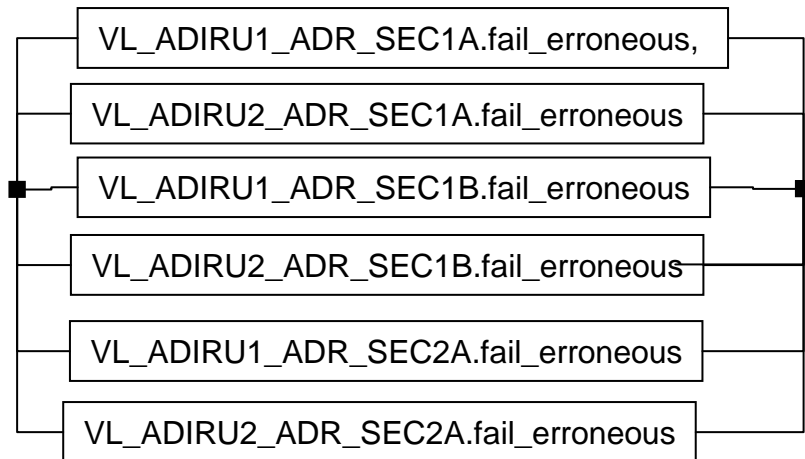
- Qualitative Safety Requirement:
 - « No double failure of dataflows between ADIRU and SEC shall cause the loss of all SEC functions »
 - « No double failure of dataflows between ADIRU and SEC shall cause the undetected erroneous behaviour of all SEC functions »



Safety Requirement Assessment

- Automatic Generation of the fault-tree from the model

- Generation of minimal cut sets

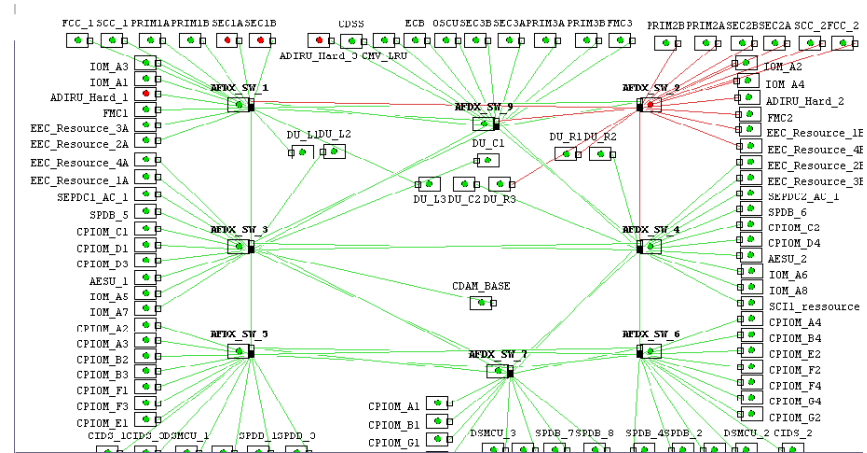


- Computation of probabilities

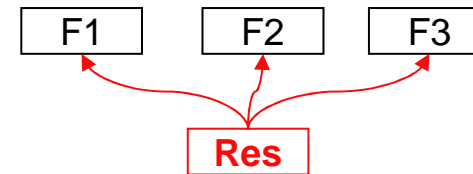
Size	Loss	Erroneous
1	0	0
2	0	0
3	0	0
4	0	0
5	0	0
6	5832	8748
7	1944	972
8	216	0
9	8	0
Total	8000	9720
Proba	2.0 e-24	3.0 e-24

Hardware + Allocation models

- Hardware model
 - very basic model

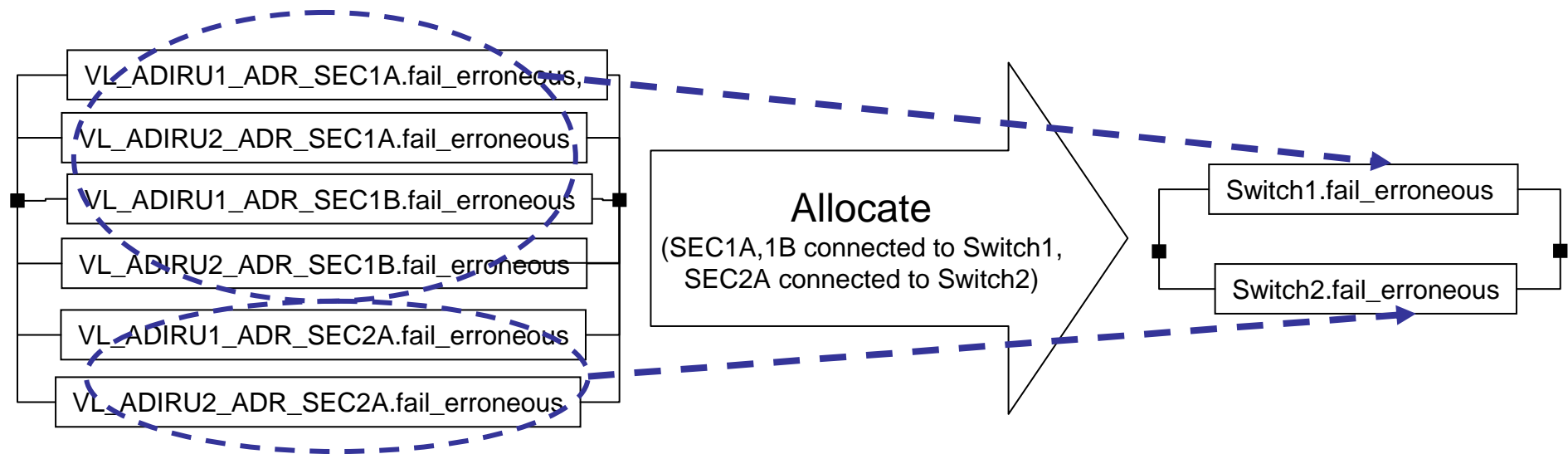


- Allocation model
 - Common cause failure
 - Use Broadcast to group failure event of the resource with failure events of all supported functions and data flows



Impact of allocation on Safety requirements

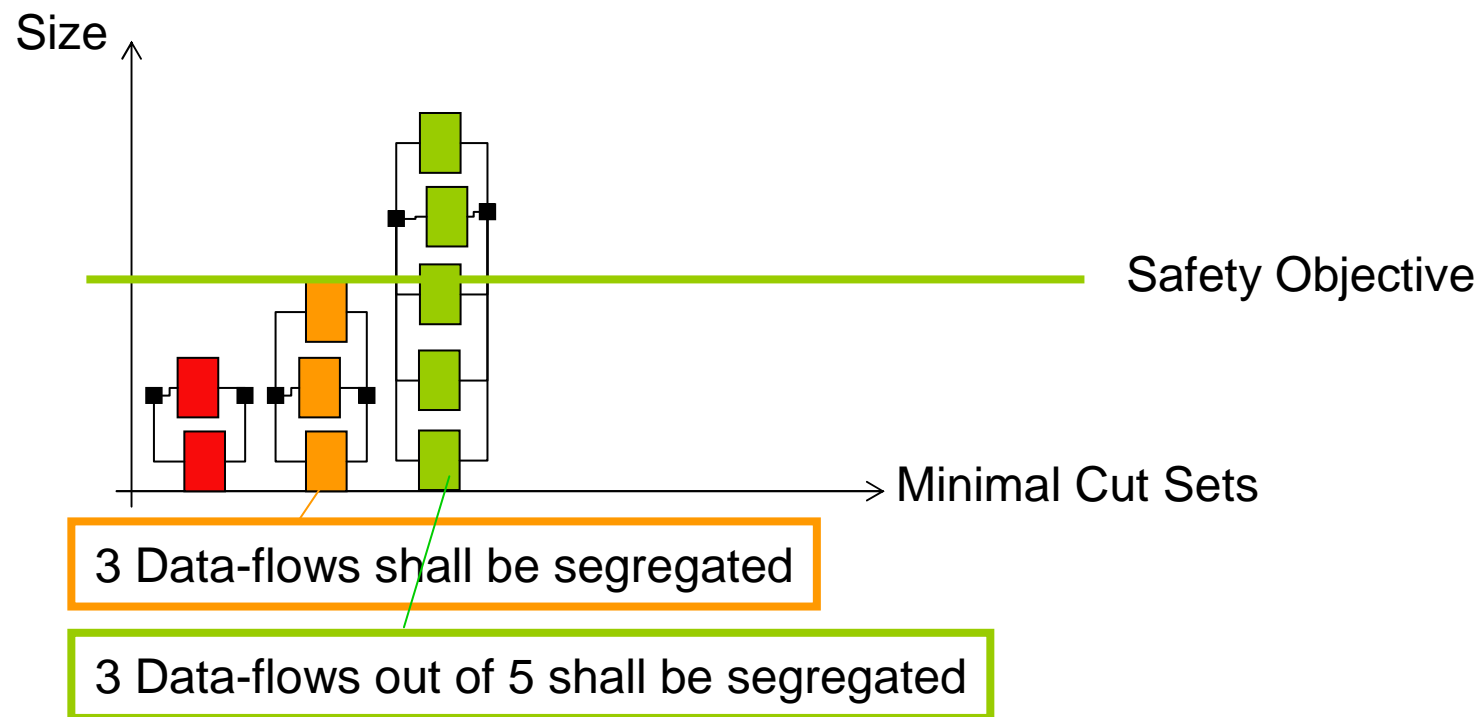
- Allocation of shared resources to functions and data-flows creates Common Mode Failures.



- Compare before/after allocation:
 - Decrease size of minimal cut sets,
 - increase probability of FC occurrence
 - Is this impact acceptable ?

Derivation of Segregation Requirements

- Extract segregation requirements from the safety assessment results in order to avoid allocation common mode failures



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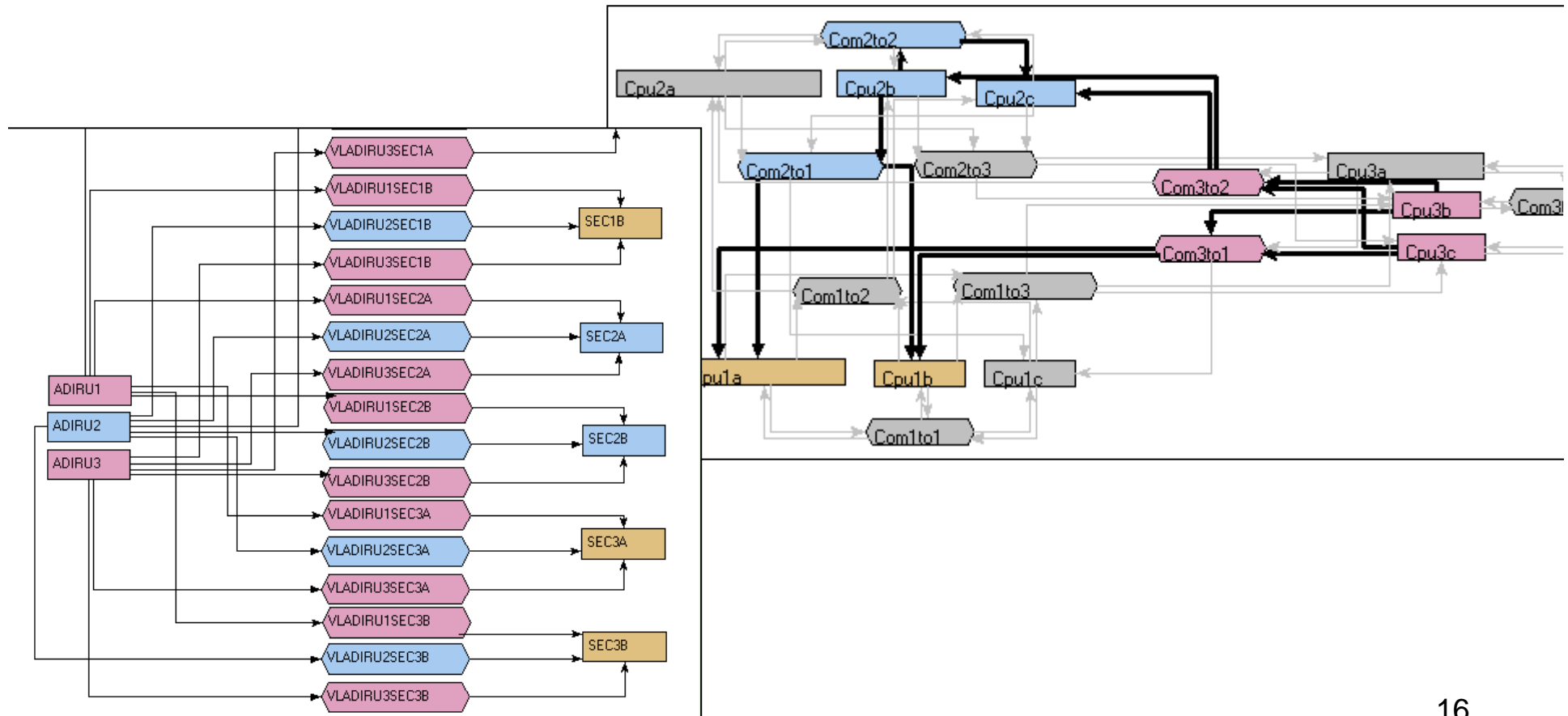
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Allocation Generation by Constraint Solving

- Formalisation of allocation constraints
 - $\{0,1\}$ linear inequalities.
- Variables :
 - $\text{allotc}(\text{task}, \text{cpu}) : \{0,1\}$
 - $\text{allobd}(\text{data}, \text{bus}) : \{0,1\}$
 - $\text{connected}(\text{cpu}, \text{bus})$ or $\text{connected}(\text{bus}, \text{cpu}) : \{0,1\}$
- Inequalities
 - Any task has to be allocated to one and only cpu
$$\text{allotc}(t, c_1) + \dots + \text{allotc}(t, c_n) = 1$$
 - Two segregated tasks should not be allocated to the same cpu
$$\text{allotc}(t_1, c) + \text{allotc}(t_2, c) + \text{segregated}(t_1, t_2) \leq 2$$
 - A connection (C,B) is used if there exists a data flow D and its producing task T such D is allocated to B and T is allocated to C.
- Criterion
 - Minimise the number of used connections

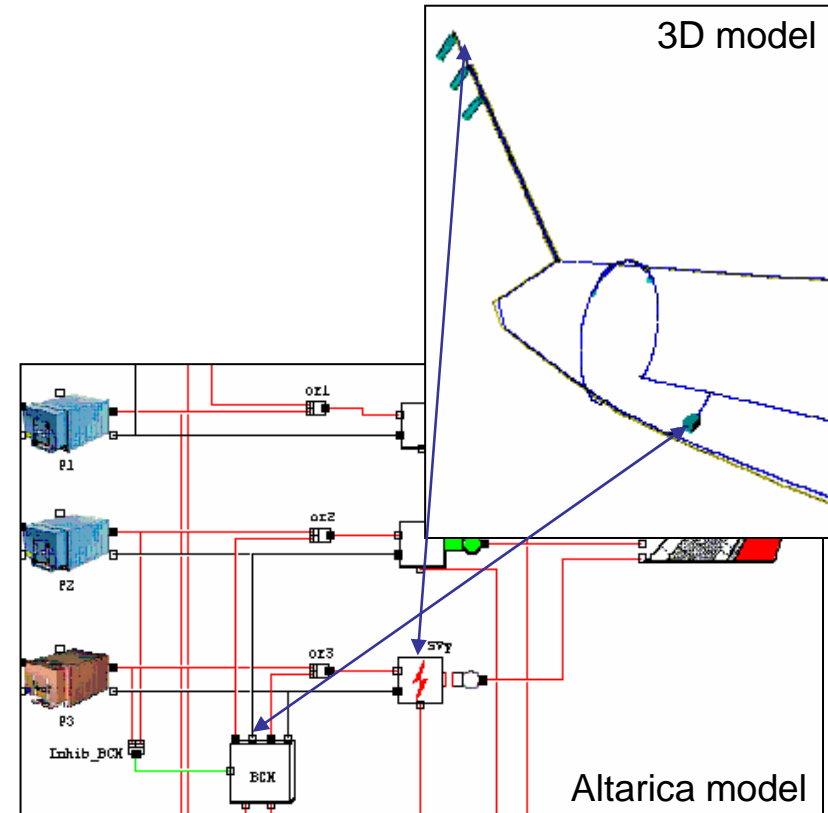
Tool Support for Constraint Solving

- Generation of constraints
- Call to solvers (ILOG solver, satzoo)
- Visualisation of allocations

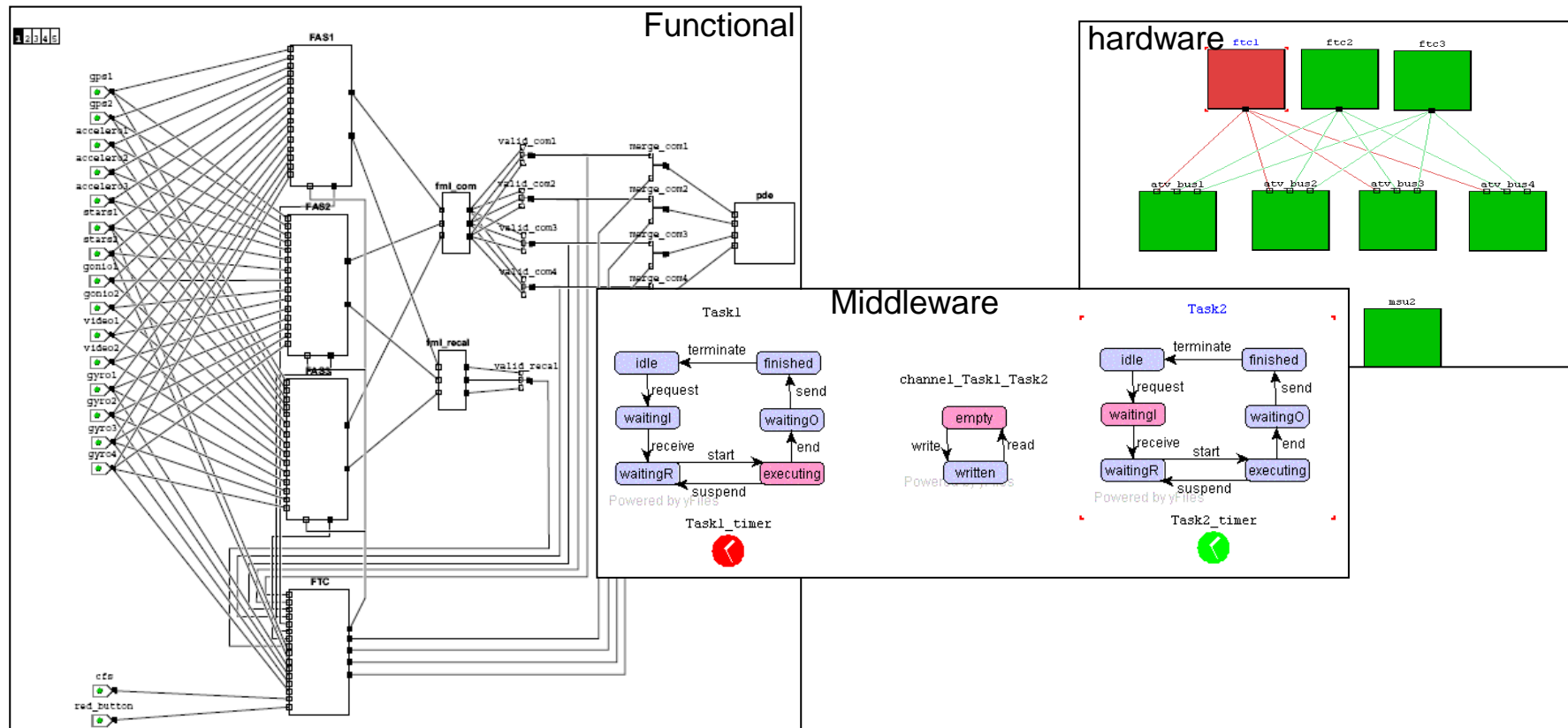


Installation Related Assessment

- Assess the impact of equipment installation on Safety Requirements
- Link functional architecture model with Digital Aircraft mockup (CATIA, IRIS)
 - Similar to the modelling of allocation of functions on hardware
- Study the effect of tyre or engine burst on functions



ATV Case Study



- Software dependability oriented model:
 - More detailed functional Architecture, simpler hardware model
 - Add a model of middleware services « between » functional view and Hardware architecture view to study new kind of failure propagations in the temporal domain

Automated Production of Altarica models

- Generate dependability models
 - Industrial need : decrease the modelling effort
 - AADL (Avionics Architecture Description Language) to Altarica model transformation
 - AADL models structured in layers
 - Hardware and allocation : similar to Altarica, easy to transform
 - Functional architecture : more expressive, not so easy to transform...
 - AADL Error Annex
 - AADL special notation for failure propagation models
 - Adapted for Software failure propagation modelling
 - Limited tool-support (by now)

Conclusion – Further work

- Requirement driven engineering
 - Organize the design activities
 - Define what models should be built and what analysis should be performed
- Models for software dependability
 - Model more accurately software
- Optimise avionics architecture with respect to several viewpoints :
 - real-time performances, operational reliability, installation, Electro-magnetic Interference, ...